

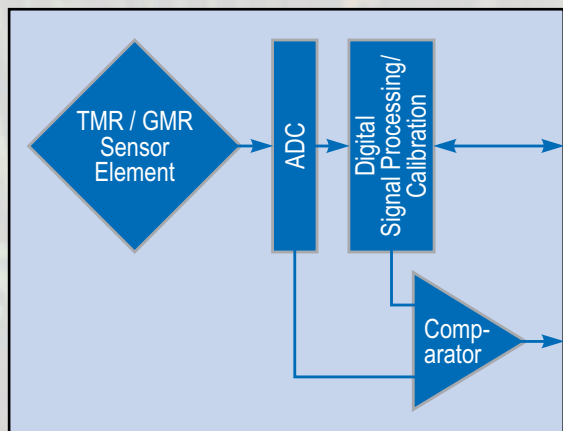
NEW!
Ultrasensitive
Sensors

Magnetic Sensors *Short-Form Catalog*

Smart Sensors

Factory Calibrated with I²C and SPI Interfaces

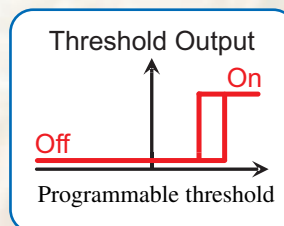
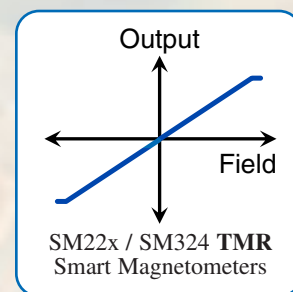
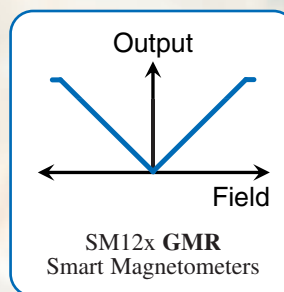
A full line of smart magnetometers and smart angle sensors combine the precision and high sensitivity of our industry-leading GMR/TMR sensors with sophisticated digital signal processing to create devices with unparalleled accuracy. This allows precision magnetic sensing with lower part counts and faster development cycles than ever before. NVE Smart Sensors come in ultraminiature, 2.5 x 2.5 mm DFN6 packages.



Smart Sensor Block Diagram.

I²C or SPI Interface

Programmable Threshold (I²C magnetometers)



SM-Series smart magnetometers are ideal for proximity and noncontact current sensing in robotics, mechatronics, and automotive applications. Key specifications are summarized below:

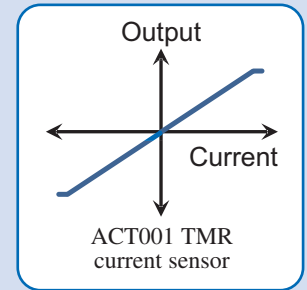
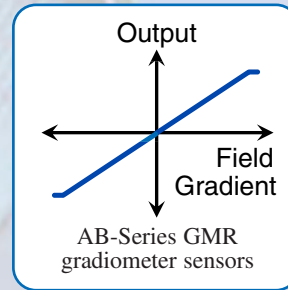
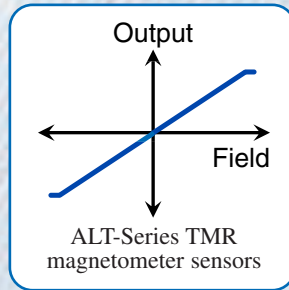
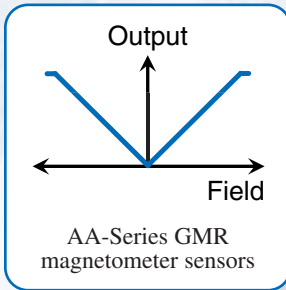
SM-SERIES SMART MAGNETOMETERS						
Part Number	Technology	Accuracy	Update Rate	Range	Outputs	Features
SM124-10	Omnipolar GMR	5%	10 kSps	0 to 1 mT	I ² C; Digital Threshold	General Purpose Proximity Sensing
SM125-10				0 to 4 mT		
SM223-10	Bipolar TMR	2%	15 kSps	-1 to +1 mT	I ² C; Digital Threshold	Current or Proximity Sensing
SM228-10				-15 to +15 mT		
SM225-10				SPI		
SM324-10	Bipolar TMR	0.3%	300 Sps	-2 to +2 mT	I ² C; Digital Threshold	Ultraprecise Current or Proximity Sensing

ASR-Series smart angle sensors cover a range of robotics, mechatronics, and automotive applications:

ASR-SERIES SMART TMR ANGLE SENSORS				
Part Number	Accuracy	Update Rate	Operating Field Range	Outputs
ASR002-10	2°	12.5 kSps	6 to 20 mT	High-speed SPI
ASR012-10				I ² C; PWM
ASR003-10		10 kSps		SPI angle and field magnitude
ASR022-10	±3 LSB	10 kSps		ABZ; DIR (encoder emulation)

Analog Bridge Sensors

Versatile, Sensitive, and Accurate



GMR and TMR analog bridge sensors are ideal for a wide range of magnetic sensing, including position and current. **AA-Series** GMR magnetometers are omnipolar, providing the a positive output for either field polarity. **AB-Series** sensors are differential devices (gradiometers), with bipolar outputs. **H-subtype** magnetometers and gradiometers have higher sensitivity. **L-subtype** magnetometers use low-hysteresis GMR materials for precise low-field measurements. The **K-subtype** is a kilooersted range high-field magnetometer. **ALT-Series** TMR magnetometers are high sensitivity, low hysteresis, and bipolar. The **ACT001** current sensor has a TMR sensor element and an integrated current strap.

ANALOG MAGNETOMETERS								
Part Number	Technology	Saturation (mT)	Linear Range (mT)		Typical Sensitivity (mV/V/mT)	Typical Bridge Resistance	Feature	Package
			Min.	Max.				
AAH002-02	Omnipolar GMR	0.6	0.06	0.3	150	2 k Ω	Ultra-high sensitivity	SOIC8
AAL002-02	Low-hysteresis Omnipolar GMR	1.5	0.15	1.05	35	5 k Ω	Low hysteresis	
AAL004-10						2.2 k Ω		
AAL024-10						Bipolar TMR	± 0.3	-0.2
ALT021-10	DFN6							
ALT023-10								
ALT025-10								
AA002-02	Omnipolar GMR	1.5	0.15	1.05	35	5 k Ω	General purpose	SOIC8
AA003-02		2	0.2	1.4	26			MSOP8
AA004-00		5	0.5	3.5	10			SOIC8
AA004-02		10	1	7	5	30 k Ω	Low power	MSOP8
AA005-02		5	0.5	3.5	10		High field	
AA006-00		50	5	45	1		5 k Ω	
AA007-00		400	40	250	0.033	3.5 k Ω	Very high field; small	1.1 mm x 1.1 mm DFN4
AAK001-14		Bipolar TMR	± 10	-10	+10	0.033	20 k Ω	
ALT025-14		Omnidirectional TMR	1500	50	800	0.025	1 M Ω	Ultrahigh field; ultralow power

ANALOG GRADIOMETERS					
Part Number	Saturation (mT)	Linear Range (mT)		Typical Bridge Resistance	Package
		Min.	Max.		
AB001-02	25	1	17.5	2.5 k Ω	SOIC8
AB001-00	25	1	17.5	2.5 k Ω	MSOP8
ABH001-00	7	0.5	4	1.2 k Ω	MSOP8



ANALOG CURRENT SENSOR			
Part Number	Linear Range	Output Sensitivity	Package
ACT001-10	± 0.5 A	40 mV/V-A	DFN6

GMR Switch Sensors

Sensitive and Precise

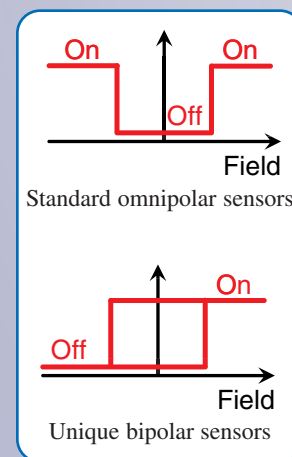
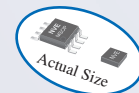
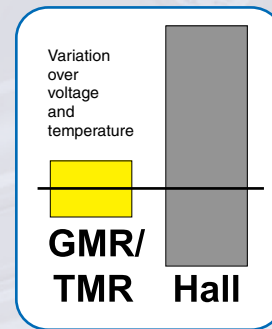
GMR Switch Precision Digital Sensors provide more precise operate points than Hall-effect or other conventional sensors. Magnetic operate points range from 0.4 mT (the world's most sensitive magnetic switches) to 8 mT.

AD-Series digital sensors are available with a variety of switch points and output configurations, and come in DFN6 and MSOP 8 packages. The parts have a wide 4.5 to 30 volt supply range.

AD-Series sensors are omnipolar, so a field of either polarity switches the sensor ON, and the sensor turns OFF when the field is removed.

AFL-Series sensors have supply voltages ranging from 0.9 to 5.5 volts for low-voltage and battery-powered applications.

POPULAR AD-SERIES DIGITAL SWITCHES						
Part Number	Typ. Operate Point (mT)	Supply Voltage Range	Typ. Supply Current (mA)	Output Type	Package	
AD004-00	2	4.5 to 30 V	4	Sink	MSOP8	
AD005-00	4					
AD006-00	8					
AD021-00	2					
AD022-00	4					
AD024-00	2.8					
AD024-10	2.8			Sink+Source	TDFN6	
AD621-00	2					
AD824-00	2.8			3	2 Sinks+SCP	MSOP8
ADH025-00	1			4	Sink	

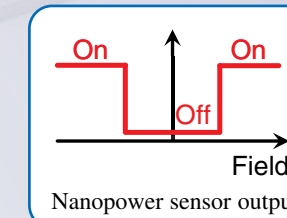


AFL-SERIES DIGITAL SENSORS					
Part Number	Typ. Operate Point (mT)	Supply Voltage Range	Output Type	Package	
AFL000-10	1	0.9 to 2V	Normally Off, Current Sink	DFN6	
AFL000-01				Die	
AFL002-10	2.8		Normally Off, Current Sink	DFN6	
AFL006-10	0.4				
AFL020-00	1		1.8 to 2.5 V	Normally On, Current Source	MSOP8
AFL030-00				Normally Off, Current Source	
AFL100-00		Normally Off, Current Sink		DFN6	
AFL100-10				Die	
AFL103-01	4	2.7 to 3.6 V	Normally Off, Current Sink	MSOP8	
AFL200-00	1				4.5 to 5.5 V
AFL300-00					

GMR and TMR Nanopower Digital Switches

Ultraminiature; Ultralow Power

Benefits:	GMR	TMR	Hall	AMR	Reed
Size	Small	Small	Small	Large	Very Large
Signal Level	Large	Very Large	Small	Medium	Switch
Sensitivity	High	Very High	Low	High	Low
Temperature	High	High	Low	Medium	Medium
Power	Low	Very Low	Low	High	Switch
Cost	Low	Low	Low	High	Low



NVE Nanopower Magnetic Switches are small enough to fit on the head of a pin and low enough power to run forever on a button cell. TMR and internally duty-cycled GMR versions reduce power consumption to nanowatts. The sensors are available with a variety of operate points and come in tiny 1.1 by 1.1 mm DFN packages.

The **ADL-** and **ADT-Series** sensors have a 2.4 to 4.2 volt supply range for lithium batteries or 3.3 volt supplies. **AHL-, AHT-,** and **AHK-Series** sensors operate as low as 0.9 volts for use with 1.5 volt batteries.

Popular **digital switch applications:**

- Cylinder position sensors
- Proximity sensors
- End-of-travel sensors

NANOPOWER SENSORS						
Part Number	Technology	Typ. Operate Point (mT)	Supply Voltage Range	Typ. Supply Current (μA)	Typ. Update Frequency	Package
ADL021-14	GMR	2	2.4 to 4.2 V	0.05	55 Hz	1.1 mm x 1.1 mm DFN4
ADL022-14		4				
ADL024-14		2.8				
ADL121-14		2				
ADL122-14		4				
ADL124-14		2.8				
ADL921-14		2				
ADL922-14		4				
ADL922NC		4 (normally closed)				
ADL924-14		2.8				
ADT922-14	TMR	4.5	0.9 to 2.4 V	35	Continuous	1.1 mm x 1.1 mm DFN4
ADT923-14		3.2				
ADT924-14		2.2				
ADT925-14		1.5				
ADK991-14		350				
AHL021-14		2				
AHL024-14		2.8				
AHL025-14	1					
AHL921-14	GMR	2	0.9 to 2.4 V	0.095	110 Hz	1.1 mm x 1.1 mm DFN4
AHL924-14		2.8				
AHL925-14		1				
AHT922-14		4.5				
AHT923-14		3.2				
AHT924-14		2.2				
AHT925-14	1.5					
AHK991-14	TMR	350	0.9 to 1.8 V	0.3	Continuous	1.1 mm x 1.1 mm DFN4
		2				

Angle and Rotation Sensors

Small, Precise, and Ultralow Power

AAT- and ADT-Series noncontact angle and rotation sensors are based on spintronic TMR elements for small size, large signals, and low power. An external magnet provides a saturating magnetic field in the plane of the sensor. The sensors work with magnetic fields from 1.5 to 20 mT. Parts come in ultraminiature 2.5 by 2.5 mm DFN6 packages.

AAT-Series angle sensors provide sine and cosine signals defining the absolute angle of rotation. Outputs are proportional to the supply voltage and peak-to-peak output voltages are much larger than conventional sensors. **AAT00x** sensors consist of two half-bridges, while **AAT10x** sensors have two full bridges with differential outputs. The **AAT006** works with extremely low fields. Available bridge resistances range from 40 kilohm typical device resistance for direct interface to simple micro-controllers, to six megohms for ultralow power.

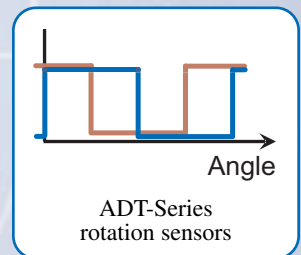
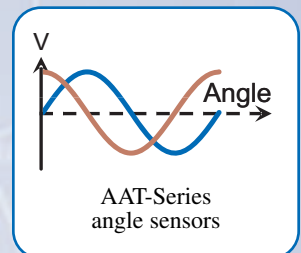
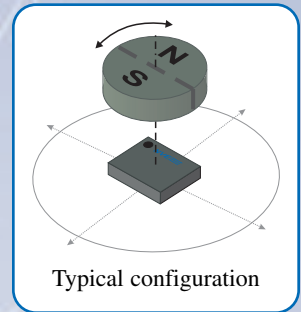
ADT-Series rotation sensors have two digital, binary outputs. The outputs are 90 degrees out of phase to provide directional information. The **ADT001** is high hysteresis for noise immunity in applications such as speed sensing; the **ADT002** is low hysteresis to provide accurate, absolute rotational information.

Key features of **AAT-** and **ADT-Series** sensors are:

- Extremely low power
- Wide airgap tolerance
- 0.5° repeatability
- Wide supply range
- -40 °C to 125 °C operating range
- Ultraminiature DFN6 package

Popular applications include:

- Rotational position sensors
- Rotational speed sensors
- Encoders
- Water meters



ADT-SERIES ROTATION SENSORS				
Part Number	Max. Error	Typ. Hysteresis	Typ. Supply Current	Package
ADT001-10	1.5°	20°	2.2 μA	DFN6
ADT002-10		4°		

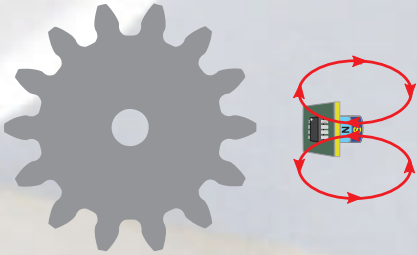
Angle	Output	
	Sin	Cos
0° to 90°	H	H
90° to 180°	H	L
180° to 270°	L	L
270° to 360°	L	H

ADT-Series rotation sensor truth table.

AAT-SERIES ANGLE SENSORS					
Part Number	Bridge Configuration	Typ. Output (ea. output; p-p)	Operating Field Range	Typ. Device Resistance	Package
AAT001-10	Half-bridge	200 mV/V	3 to 20 mT	1.25 MΩ	DFN6
AAT003-10				40 KΩ	
AAT006-10			1.5 to 10 mT	1.5 MΩ	
AAT009-10			3 to 20 mT	6 MΩ	
AAT101-10	Full-bridge	400 mV/V		625 KΩ	

Gear-Tooth and Encoder Sensors

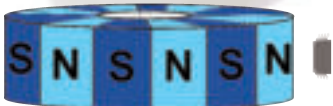
Robust and Precise



ABT-, ABL-, and AKL-Series gear-tooth sensors used with bias magnets and ferromagnetic gears.

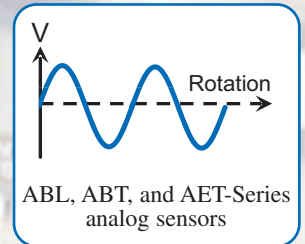
NVE has a full line of gear-tooth and encoder sensors. Gear-tooth sensors are used with ferromagnetic gears and bias magnets; encoder sensors are used with multipole magnets. These unique parts feature large signals, wide airgap tolerance, and high operating temperature.

AET-Series encoder sensors have differential TMR sensor elements that provide sinusoidal outputs from cyclic magnet poles on multipole magnets or linear scale tape. Various spacings are available for various pole pitches. Interpolation allows extremely precise rotational or linear position sensing. Double bridges provide direction information.

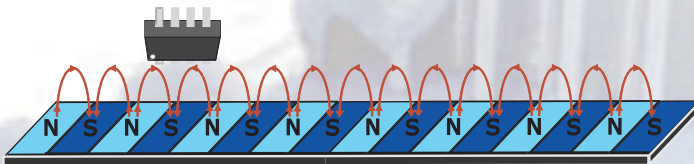


A typical AET-Series encoder sensor with a multipole magnet.

ABL-Series and **ABT-Series** analog gear-tooth sensors have differential sensor elements that provide sinusoidal outputs. Various sensor spacings are available to match a variety of gear pitches. Double bridges generate sine and cosine outputs to provide direction information. **ABL-Series** sensors use venerable GMR.



AKL-Series digital gear-tooth sensors are two-wire devices where the supply current indicates a passing tooth.



AET-Series encoder sensors used with magnetic linear scale tape.

TMR Encoder Sensors				
Part Number	Half/ Full Bridges	Pole Pitch (normal mode)	Pole Pitch (double-pitch mode)	Package
AET500-02	Half	5 mm	N/A	SOIC8
AET050F-00	Full	0.5 mm	1 mm	MSOP8
AET075F-00		0.75 mm	1.5 mm	
AET100F-00		1 mm	2 mm	
AET120F-00		1.2 mm	2.4 mm	

GMR ANALOG GEAR-TOOTH SENSORS			
Part Number	Single or Dual Bridge	Gear Pitch (mm)	Package
ABL004-00	Single	1.7 to 6	MSOP8
ABL005-00		0.8 to 1.7	
ABL006-00		0.5 to 0.8	
ABL014-00	Dual	1.7 to 6	
ABL015-00		0.8 to 1.7	
ABL016-00		0.5 to 0.8	
ABL004-10	Single	1.7 to 6	DFN6
ABL005-10		0.8 to 1.7	
ABL006-10		0.5 to 0.8	
ABL014-10	Dual	1.7 to 6	
ABL015-10		0.8 to 1.7	
ABL016-10		0.5 to 0.8	

DIGITAL GEAR-TOOTH SENSORS		
Part Number	Element Spacing (mm)	Package
AKL001-12	1	DFN8
AKL002-12	0.5	
AKL003-12	0.3	

TMR ANALOG GEAR-TOOTH SENSORS			
Part Number	Single or Dual Bridge	Gear Pitch (mm)	Package
ABT250-00	Dual	0.6 to 2	MSOP8
ABT375-00		1 to 3	
ABT500-00		1.3 to 4	
ABT600-00		1.6 to 4.8	

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On the Cover

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