

Two-Wire Sensor Interfaces

Two-wire sensors are common in industrial control to simplify wiring. But for many sensors, competing constraints make designing two-wire interface circuitry tricky.

Two wire interfaces need to operate over a wide power supply range. With the sensor off, the circuit should draw a minimal residual current, typically less than 1.5 milliamps. With the sensor on, the circuit must provide enough current to drive a significant load such as a motor or solenoid.

NVE's [ADL-Series sensors](#) are perfect for two-wire applications, because their low supply voltage and low quiescent current provide plenty of design margin. Also, the ADL-Series' small package (1.1 x 1.1 x 0.45 mm) allows the parts to fit in the smallest assemblies, such as those for 3 mm-wide cylinder grooves.

A Simple Reference Circuit

Here's a simple, inexpensive reference circuit:

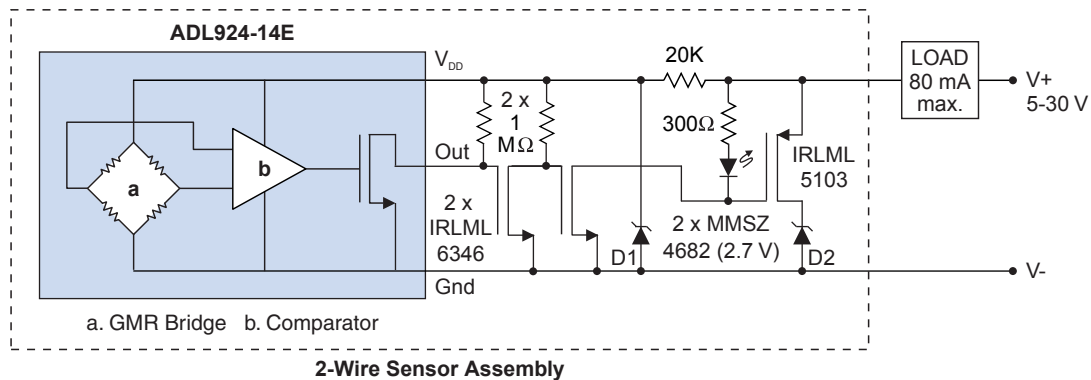


Figure 1. An inexpensive 2-wire interface reference circuit.

In this circuit, when a magnetic field is applied to the sensor, the MOSFETs turn on, turning on the LED and powering the load.

With no magnetic field and the sensor off, the residual current of the circuit is the D1 Zener diode bias current plus the sensor quiescent current. The ADL924 quiescent current is negligible, so the residual current is dominated by the Zener current, which is less than 1.5 milliamps. D1 should be a low-current Zener to allow a higher series resistor for minimal residual current.

Zener diode D1 limits the ADL925 supply voltage with the load unpowered; Zener diode D2 provides enough voltage to power the circuitry when the load is powered.

Better Voltage Regulation

A voltage regulator instead of the D1 Zener diode provides better regulation and better operating latitude over the input voltage range. This reference circuit is shown in Figure 2:

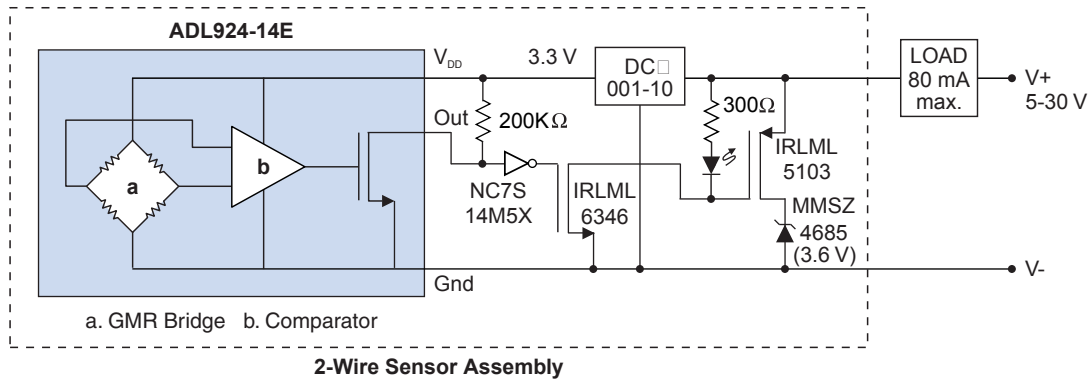


Figure 2. A simple 2-wire interface using a voltage regulator and a TinyLogic inverter.

The residual current is dominated by the regulator's quiescent current, which is less than one milliamp and relatively constant over input voltage.

The Figure 2 circuit also uses an inverter in place of one of the MOSFETs, which eliminates a resistor.

Circuit Characterization

Measured characteristics of the Figure 1 and Figure 2 reference circuits are summarized as follows:

Parameter	Symbol	Circuit	
		Figure 1	Figure 2
Min. Input Voltage (sensor on; $R_L = 100\Omega$)	V_{MIN}	5 V	3.1 V
Max. Input Voltage (sensor on; $R_L = 100\Omega$)	V_{MAX}	30 V	30 V
Residual Current ($V+ = V_{MAX} = 30 V$)	I_Q	1.3 mA	0.6 mA
Holding Current	I_H	11 mA	11 mA

Where:

V_{MIN} is the minimum input voltage for the assembly to operate, which means there is at least 2.4 volts for to the ADL924 sensor, which is its minimum supply voltage. V_{MIN} must typically be 5 volts or less.

V_{MAX} is the maximum input supply voltage, which is typically at least 24 volts. V_{MAX} is limited by the maximum voltage of the MOSFETs and component power dissipation, especially the D2 Zener diode power dissipation.

I_Q is the worst-case residual, or quiescent, current with the sensor off and the $V+$ supply at maximum. This is typically in the one milliamp range.

I_H is the holding current, which is the minimum current that must be sourced through the load with the sensor ON to ensure the sensor will operate (i.e., 2.4 volts to the sensor). Holding current for industrial control two-wire interfaces typically ranges from 3 mA to 20 mA.

Note that these are measured parameters, not worst-case specifications.

As shown in the table above, the Figure 1 reference circuit has a higher residual current than the Figure 2 circuit because of the Zener diode bias. The Figure 2 circuit has a lower minimum voltage with the better

line regulation provided by the regulator. Lower dropout regulators can be used in place of the DC001-10 for even lower minimum input voltages.

For these circuits, the holding current is dominated by the LED current, and can be reduced by reducing the LED drive.

The output current versus input voltage for the Figure 1 reference circuit is shown below:

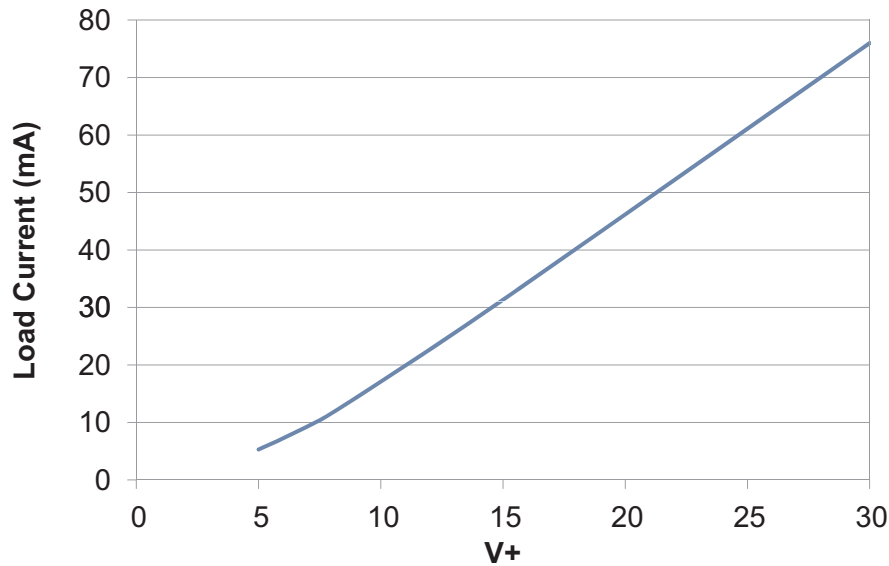


Figure 3. 2-wire interface reference circuit (Figure 1) output current versus input voltage; $R_L = 333\Omega$.

Conclusion—ADL924 Sensor Are Ideal for 2-Wire Interfaces

ADL-Series sensors are ideal for two-wire proximity sensors because of their small size, low supply voltage, and low quiescent current.

In addition to their impressive electrical specifications, ADL-Series sensors feature precise magnetic operate points. Standard ADL-Series magnetic operate points are 20 ± 5 , and 28 ± 7 oersteds, with other ranges available by special order.

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